

VOLTERIO – AUTOMATIC CONNECTION DEVICE

Conductive Hands-Free Charging System

AUTOMATIC CONDUCTIVE CHARGING SYSTEM







VOLTERIO // CONTINENTAL COLLABORATION PROJECT







background vs. foreground vs. sideground IP

AUTOMATIC CHARGING – USE CASES











Comfort Charging for EVs and PHEVs

- Premium OEMs
- Volume OEMs (Home & Public Charging)

Autonomous Driving EVs

- Robo taxis
- ► Fleets; Automatic valet parking

Smart Grids & HPC

Vehilce-to-grid, Peak-shaving, virtual power plants ...

Industrial and Heavy-duty Vehicles

- Automated Container Terminals, Mining, ...
- ▶ Urban Logistics, Electric Trucks, Electric Buses ...

AUTOMATIC CHARGING - OVERVIEW





AUTOMATIC SIDE COUPLERS (Concept stage)





KUKA wall mounted robot



Tesla "snake charger" concept



Volkswagen mobile CarLa robot (2018)



Volkswagen charging concept (2019)

Problems of ACD-S:

- Requires complex robotics with "Six degrees of freedom"
- Complicated and precise positioning
- Huge space requirements
- Expensive robotics



Connector with pins

- \rightarrow Not rotational symmetric
- \rightarrow Not ideal for a robotic connection







 \rightarrow Conical shaped Connector for Self-Centering

 \rightarrow 360° Contacts instead of pins

VOLTERIO

360° SELF-CENTERING VOLTERIO CONNECTOR





VOLTERIO CONNECTOR IN THE VEHICLE UNIT





Connector at the Vehicle Unit (97 x 97 x 18 mm) \rightarrow Male Counterpart with moveable contact body

OEM REQUIREMENTS

Onboard (Vehicle Unit)

- Low cost, small packaging size (minimal height)
- Minimal complexity in the vehicle -> low development risk
- Easy homologation
- HV-safety due to multiple sealings

Offboard (Ground Unit)

- No homologation required
- Robust, low cost 3-axis robot
- High charging capacity (AC & DC)
- HV-components completly sealed
- High contact quality
- Protected against dirt, moisture, corrosion





VEHICLE APPROACH



- WLAN Communication between VU and GU according to ISO 15118
- Pairing >5m, then guiding to the final parking position within the working area of the ACD

Vehicle Unit (placement in the front of the underbody)





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Final parking position for automatic connection

WORKING AREA OF THE CHARGING ROBOT



- Inlet's center of the vehicle unit must be within the working area of the ACD
- Theoretical working area can be described between the two concentric circle segments
 - -> can be limited to the green circle (\emptyset > 400 mm)



Ground Unit (GU) L 800 mm x W 420 mm x H 67 mm















The entire robot rotates counter-clockwise until it reaches the the position straight under the VU's Inlet





Charging starts automatically when docking is accomplished and a secure connection is ensured Minimal underbody clearance for an automatic connection is <85 mm, maximal height for docking is 250 mm

DOCKING- SIDE VIEW







CONNECTOR INTERFACE - UNDERBODY VIEW







VEHICLE UNIT - PACKAGING

Dimensions in mm









INTEROPERABILITY

Use Case Primarily for Charging at Home (Garages/Carparks)

- No complicated Installation
- ► → Just Plug and Play and On-The-Ground Solution

Public Charging (Street Charging, Primarily for Outdoor)

- Robot will be fully flush embedded in the ground
- Fully interoperable system, different use case



Volterio PRO



INTELLECTUAL PROPERTY & STANDARDIZATION ACTIVITIES

- 8 patent families in most important markets worldwide
 - Charging process
 - 360° hpc connector
 - Different robot variants
 - Positioning system
- Standardization Bodies VDE/DKE, VDA, ISO, IEC
- Core Member in CharlN (Charging Interface Initiative e.V.)
- Support from industry leaders











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